

Ref #	Hits	Search Query	DBs	Default Operator	Plurals	Time Stamp
S1	212	(623/24).CCLS.	US-PGPUB; USPAT	OR	OFF	2006/02/01 12:15
S2	42822	mems	US-PGPUB; USPAT	OR	ON	2006/02/01 12:15
S3	4	S1 and S2	US-PGPUB; USPAT	OR	ON	2006/02/01 12:18
S4	37805	prosthesis	US-PGPUB; USPAT	OR	ON	2006/02/01 12:18
S5	208628	hinge	US-PGPUB; USPAT	OR	ON	2006/02/01 12:59
S6	611901	sensor	US-PGPUB; USPAT	OR	ON	2006/02/01 12:19
S7	1590556	measures	US-PGPUB; USPAT	OR	ON	2006/02/01 12:21
S8	91019	angular adj position	US-PGPUB; USPAT	OR	ON	2006/02/01 12:21
S9	5372	S7 with S8	US-PGPUB; USPAT	OR	ON	2006/02/01 12:22
S10	74793	robot\$	US-PGPUB; USPAT	OR	ON	2006/02/01 12:22
S11	92	S9 and S2	US-PGPUB; USPAT	OR	ON	2006/02/01 12:59
S12	84	S11 and S6	US-PGPUB; USPAT	OR	ON	2006/02/01 12:25
S13	4	S12 and S4	US-PGPUB; USPAT	OR	ON	2006/02/01 12:48
S14	10	S12 and S10	US-PGPUB; USPAT	OR	ON	2006/02/01 12:57
S15	1	((active adj articular) adj prostheses)	US-PGPUB; USPAT	OR	ON	2006/02/01 12:58
S16	3198	S9 and S6	US-PGPUB; USPAT	OR	ON	2006/02/01 12:59
S17	533699	hinge pivot	US-PGPUB; USPAT	OR	ON	2006/02/01 12:59
S18	653	S16 and S17	US-PGPUB; USPAT	OR	ON	2006/02/01 14:51
S19	220345	control adj unit	US-PGPUB; USPAT	OR	ON	2006/02/01 13:01
S20	126	S18 and S19	US-PGPUB; USPAT	OR	ON	2006/02/01 14:36
S21	61401	potentiometer	US-PGPUB; USPAT	OR	ON	2006/02/01 14:36
S22	525	S16 and S21	US-PGPUB; USPAT	OR	ON	2006/02/01 14:52

S23	277326	actuator	US-PGPUB; USPAT	OR	ON	2006/02/01 14:55
S24	1321757	angular angle	US-PGPUB; USPAT	OR	ON	2006/02/01 14:55
S25	525	S22 and S24	US-PGPUB; USPAT	OR	ON	2006/02/01 14:56
S26	110603	S4 S10	US-PGPUB; USPAT	OR	ON	2006/02/01 14:56
S27	61	S25 and S26	US-PGPUB; USPAT	OR	ON	2006/02/01 14:56

AS,
S.N. W/825,966